### **HQA Lecture 18**

### I. Friedel oscillations

### **II.** Spin lattices

**III. Walkers on gentle slopes** 

## Hydrodynamic spin lattices

#### Article

## Emergent order in hydrodynamic spin lattices

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## Effect of outer layer thickness

• adopt the geometry considered in the Friedel oscillations analog



### **Tighter trapped states emerge for decreasing liquid heights!**

## Variable bottom topography

Bottom topography can be exploited to induce effective attractive potentials.



 $D \sim 10 \,\mathrm{mm}$   $h \sim 1 \,\mathrm{mm}$ 



Drop trapped over a submerged well

A submerged well may serve to stabilize a hydrodynamic "spin state"

## Effect of memory on individual spin states



• circular spin states destabilize to wobbling trefoils at high memory

### SPIN LATTICES OF WALKING DROPLETS



Control parameters

- Geometry h, L, D
- Vibrational acceleration  $\gamma/\gamma_F$
- Drop size
- Frequency



# Spin dynamics become coupled through wave-mediated interactions!

The pair-pair coupling can be controlled through several parameters

### CHARACTERIZING COLLECTIVE BEHAVIOR



#### Spin-spin correlation

$$\chi = \langle S_i, S_j \rangle = \frac{1}{N} \sum_{i \sim j} S_i S_j$$
  
 $i \sim j$  : nearest neighbors  
 $N$  : number of pairs  
Magnetization  $M = \sum_{i \sim j}^{N} S_i$ 

i=1

Limiting configurations



## The influence of bouncing phase on spin correlations

• correlations most pronounced when all droplets are bouncing in phase



## Varying vibrational acceleration



#### Vibrational acceleration plays the role of an effective temperature.

L = 17.7 mm







Preferred antiferromagnetic order

$$L = 17.7 \text{ mm}$$

$$\gamma/\gamma_F = 0.82$$



$$L = 17.7 \text{ mm}$$
  $\gamma/\gamma_F = 0.86$ 

• fix geometry, increase memory slightly



#### Preferred antiferromagnetic order

L = 13.2 mm  $\gamma/\gamma_F = 0.86$  • fix memory, alter lattice spacing L

 $\chi_A = 0.81$ 





 $\gamma/\gamma_F = 0.86$ 

### VARYING WELL SPACING



Transition through lattice spacing!



 $L=17.7~\mathrm{mm}$ 





antiferromagnetic  $\langle \chi \rangle < 0$ 

L = 14.9 mm





ferromagnetic  $\langle \chi \rangle > 0$ 



### INTERACTION POTENTIAL



Low memory 
$$(Me \to 0)$$
  
 $h_j(\mathbf{x}, t) = \frac{AC_f}{T_F} \int_{-\infty}^t J_0(k_F |\mathbf{x} - \mathbf{x}_j(s)|) e^{-\frac{(t-s)}{T_F Me}} ds$   
 $\downarrow$   
 $h_j(\mathbf{x}, t) \sim J_0(k_F |\mathbf{x} - \mathbf{x}_j(\phi_j)|)$ 

#### **Circular motion**

$$\mathbf{x}_{j} = (r \cos \phi_{j}, r \sin \phi_{j})$$
$$\mathbf{x}_{i} = (L + r \cos \phi_{i}, r \sin \phi_{i})$$

Force in direction of motion

 $F_{i} = -\nabla h_{j}(|\mathbf{x}_{i}(\phi_{i}) - \mathbf{x}_{j}(\phi_{j})|) \cdot (-\sin \phi_{i}, \cos \phi_{i})$ Expand for  $r \ll L$  $F_{i} = A(\cos \phi_{i} - \cos \phi_{j}) \sin \phi_{i} - B(\sin \phi_{i} - \sin \phi_{j}) \cos \phi_{i} + \dots$ 

 $U(\phi_i, \phi_j) = \alpha |\cos \phi_i - \cos \phi_j|^2 + \beta |\sin \phi_i - \sin \phi_j|^2$ 

### **MODELING**

Kuramoto-like ODE model



$$U(\phi_i, \phi_j) = \alpha |\cos \phi_i - \cos \phi_j|^2 + \beta |\sin \phi_i - \sin \phi_j|^2$$



### **MECHANISM**



## **EXTERNAL FIELD**





#### Lorentz force

on moving charge in magnetic field  $\mathbf{F}_q = q\mathbf{v} \times \mathbf{B}$ 

### **Coriolis force**

on moving mass in rotating frame  $\mathbf{F}_C = 2m\mathbf{v} \times \mathbf{\Omega}$ 

### **CORIOLIS FORCE AS CONTROL PARAMETER**



$$L = 13.2 \text{ mm} \qquad \gamma/\gamma_F = 0.86$$



L = 17.7 mm

 $\gamma/\gamma_F = 0.82$ 



#### **COLLECTIVE DYNAMICS IN 2D LATTICES?**

 $D = 13 \text{ mm} \mid L = 17.7 \text{ mm}$ 



**Collective dynamics are robust in 2D!** 

**Effect of lattice geometry?** 





Antiferromagnetic order geometrically frustrated



## Summary

- well topography may stabilize hydrodynamic spin states
- wave-mediated interactions may lead to long-range spin-spin correlations
- analog ferromagnetic and antiferromagnetic states
- correlations may be altered, reversed using system geometry and memory
- memory plays a role analogous to temperature in altering emergent states
- rotation may also prompt transitions between anti- and ferromagnetic states
- qualitative behavior captured by reduced theoretical model

## **Future directions**

- theoretical characterization of spin waves sweeping through the lattice
- provides a possible platform for Bell tests
- current theoretical models used to justify emergent behavior are nonlocal

## Walkers on shallow slopes

• droplets feel lower boundary for sufficiently shallow layers, h < 0.6cm



## **Bouncer on a slope**



6

4

 $\mathbf{2}$ 

1.8

 $v \pmod{s}$ 



### Walkers on a cone

• execute circular orbits or more complex periodic or quasiperiodic orbits





FIG. 4. A regime diagram indicating the different motions observed for droplets above conical bottom topography. Dashed lines indicate approximate transitions between different types of motion. Representative trajectories are shown in figure 5. No motion was observed in the pale green region in the lower left.

FIG. 5. Orbits arising for various drop sizes and vibrational accelerations. First column: droplets with radius R = 0.32 mm, with  $\gamma/\gamma_F = a$ ) 0.89, b) 0.9, c) 0.91 and d) 0.93. Middle column: R = 0.36 mm, with  $\gamma/\gamma_F = a$ ) 0.85, f) 0.88, g) 0.89, and h) 0.92. Third column: R = 0.38 mm, with  $\gamma/\gamma_F = i$ ) 0.86, k) 0.87 and l) 0.9. The color bar at the left defines the droplet speeds. A 5 mm grid is presented for scale.

## **Theoretical modeling**

Topography:



Wave form: 
$$\eta(\mathbf{x},t) = \frac{A}{T_F} \int_{-\infty}^t \left[1 - k_F \alpha \hat{\mathbf{n}} \cdot (\mathbf{x} - \mathbf{x}_p(s))\right] J_0(k_F |\mathbf{x} - \mathbf{x}_p(s)|) e^{-\frac{t-s}{T_M}} ds.$$

Trajectory equation in the weak acceleration limit:

 $h(\epsilon \mathbf{x}) = h_0 + \epsilon \, \mathbf{x} \cdot \hat{\mathbf{n}},$ 

$$\frac{d}{dt} (\kappa \gamma_B \mathbf{v}) + \mathbf{v} \left[ 1 - \frac{\beta}{v^2} \left( 1 - \frac{1}{\sqrt{1 + v^2}} \right) - \frac{\alpha \beta (\mathbf{v} \cdot \hat{\mathbf{n}})}{(1 + v^2)^{3/2}} \right] = \frac{\alpha \beta}{\sqrt{1 + v^2}} \hat{\mathbf{n}}.$$
where  $\gamma_B(\mathbf{v}) = 1 + \frac{\beta}{2\kappa(1 + |\mathbf{v}|^2)^{3/2}}, \quad \beta = \frac{mgAk_F^2 T_F M_e^2}{D}$ 
Downslope force:  $\mathbf{F}_D = \frac{\alpha \beta}{\sqrt{1 + |\dot{\mathbf{x}}|^2}} \hat{\mathbf{n}}$  drives drop into deeper fluid
Anisotropic drag:  $\mathbf{D}_W = -\frac{\alpha \beta (\dot{\mathbf{x}} \cdot \hat{\mathbf{n}}) \dot{\mathbf{x}}}{(1 + |\dot{\mathbf{x}}|^2)^{3/2}}$  favors motion into deeper fluid,
vanishes for azimuthal motion

### **Bouncer on a slope**

$$\frac{d}{dt}\left(\kappa\gamma_{B}\mathbf{v}\right) + \mathbf{v}\left[1 - \frac{\beta}{v^{2}}\left(1 - \frac{1}{\sqrt{1+v^{2}}}\right) - \frac{\alpha\beta(\mathbf{v}\cdot\hat{\mathbf{n}})}{(1+v^{2})^{3/2}}\right] = \frac{\alpha\beta}{\sqrt{1+v^{2}}}\hat{\mathbf{n}}.$$

where 
$$\gamma_B(\mathbf{v}) = 1 + \frac{\beta}{2\kappa(1+|\mathbf{v}|^2)^{3/2}}, \quad \beta = \frac{mgAk_F^2 T_F M_e^2}{D} \quad \alpha = \tan\theta \frac{(1-\tanh^2(k_F h_0))}{\tanh(k_F h_0)}$$

Seek drifting solution:  $\mathbf{x}_p(t) = u_D t \hat{\mathbf{n}}_p$ 



### **Bouncer on a cone**

$$\frac{d}{dt} \left(\kappa \gamma_B \mathbf{v}\right) + \mathbf{v} \left[ 1 - \frac{\beta}{v^2} \left( 1 - \frac{1}{\sqrt{1+v^2}} \right) - \frac{\alpha \beta (\mathbf{v} \cdot \hat{\mathbf{n}})}{(1+v^2)^{3/2}} \right] = \frac{\alpha \beta}{\sqrt{1+v^2}} \hat{\mathbf{n}}.$$
where  $\gamma_B(\mathbf{v}) = 1 + \frac{\beta}{2\kappa(1+|\mathbf{v}|^2)^{3/2}}, \quad \alpha = \tan \theta \frac{(1-\tanh^2(k_F h_0))}{\tanh(k_F h_0)}.$ 

Seek orbital solutions:  $\mathbf{x}_p(t) = r_0 (\cos \omega t, \sin \omega t)$ 

$$\kappa \gamma_B r_0 \omega^2 = rac{lpha eta}{(1+(r_0 \omega)^2)^{1/2}}, \ r_0 \omega = rac{eta}{r_0 \omega} \left(1-rac{1}{\sqrt{1+(r_0 \omega)^2}}
ight)$$

To find: 
$$u_0 \equiv |r_0\omega| = \frac{1}{\sqrt{2}} \left(-1 + 2\beta - \sqrt{1 + 4\beta}\right)^{1/2}$$
 free walking speed

Orbital frequency  $\omega = \frac{\pm \alpha \beta}{\kappa \gamma_B u_0 \sqrt{1 + u_0^2}}$  and radius  $r_0 = \frac{\kappa \gamma_B u_0^2 \sqrt{1 + u_0^2}}{\alpha \beta}$ 



FIG. 6. (a) Dependence of the time-averaged mean radius on the normalized vibrational acceleration  $\gamma/\gamma_F$ , for each of the three drop sizes. Dashed lines indicate the minimum and maximum distance from the origin attained on these trajectories. (b) Dependence of the nondimensional observed mean radius,  $k_F \bar{r}$ , on the dimensionless group  $\frac{\kappa \gamma_B u_0^2 \sqrt{1+u_0^2}}{\beta}$ . Phase parameters of  $\sin \Phi = 0.25, 0.3$  and 0.45 were used for droplets with radius R = 0.32, 0.36 and 0.38 mm respectively, in order to match the onset of motion with the walking threshold  $\gamma_W$ . These are in line with values used in previous studies [43, 47]. The dashed curve indicates a line of best-fit, with slope 0.06. Circles denote circular trajectories; diamonds denote all others.

## Summary

- slowly-varying topography difficult to model: spatially dependent memory
- topography induces down-slope force and anisotropic drag
- conical bottom topography supports orbital motion

### **Interesting question**

To what extent can we think of topographic anomalies as the generators of forces?

- only in a limited number of special cases
  - *E.g.1* Walkers interacting with pillars, wells
  - E.g.2 Walkers orbiting above a conical substrate
- force generally depends on history, manner of approach