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The interaction of a walking droplet and a submerged pillar: From scattering to the logarithmic spiral

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Millimetric droplets may walk across the surface of a vibrating fluid bath, propelled forward by their own guiding or “pilot” wave field. We here consider the interaction of such walking droplets with a submerged circular pillar. While simple scattering events are the norm, as the waves become more pronounced, the drop departs the pillar along a path corresponding to a logarithmic spiral. The system behavior is explored both experimentally and theoretically, using a reduced numerical model in which the pillar is simply treated as a region of decreased wave speed. A trajectory equation valid in the limit of weak droplet acceleration is used to infer an effective force due to the presence of the pillar, which is found to be a lift force proportional to the product of the drop’s walking speed and its instantaneous angular speed around the post. This system presents a macroscopic example of pilot-wave-mediated forces giving rise to apparent action at a distance. *Published by AIP Publishing.*
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A small droplet can bounce indefinitely on a vibrated liquid bath and move horizontally through interactions with its own wave field. In the absence of boundaries, these walking droplets walk in a straight line at a constant speed. In the present study, we demonstrate that the presence of a submerged circular pillar can dramatically alter the trajectory through its influence on the droplet’s guiding wave field. Specifically, the wave-mediated interaction between the submerged pillar and the droplet can lead to simple scattering events or to the droplet departing the pillar along a logarithmic spiral.

By virtue of their spatial delocalization, the walkers exhibit several dynamical features previously thought to be peculiar to the microscopic realm, including tunneling,^{6,7} quantized orbits^{8,9} and orbital level splitting in a rotating frame,¹⁰ doubly quantized orbits in a harmonic potential,^{11,12} and wave-like statistics in confined geometries.^{13–15} The system has recently been reviewed and its relation to the modern extensions of de Broglie’s double-solution pilot-wave mechanics explored.^{16,17} We here demonstrate that pilot-wave-mediated local forces can give rise to apparent action at a distance when the walking droplets interact with submerged circular barriers.

I. INTRODUCTION

The logarithmic spiral is a self-similar curve arising in myriad settings in nature and classical mechanics. It has fascinated generations of scientists, including Jacob Bernoulli, who referred to the form as *Spira Mirabilis* and requested that it be inscribed on his gravestone. Logarithmic spirals arise naturally in the form of nautilus shells, the seed patterns in the heart of the sunflower and the arms of spiral galaxies. They may also arise in pursuit problems, for example, when a hawk pursues its prey while maintaining a fixed angle to its flight path.¹ When a spinning ball in flight maintains a constant angular speed while decelerating due to form drag, the resulting form is a logarithmic spiral.² Dirac’s classical theory of radiating electrons predicts that an electron will follow a logarithmic spiral in the presence of a uniform magnetic field.³ We here report an unexpected new example of the emergence of a logarithmic spiral in a hydrodynamic pilot-wave system.

Couder *et al.*⁴ discovered that a millimetric drop placed on the surface of a vibrating bath may interact with its own wave field in such a way as to walk steadily across the bath.⁵ The resulting “walkers” are spatially extended objects comprising both droplet and accompanying guiding or “pilot”

II. EXPERIMENTAL SETUP

In our experiments, a bath of silicon oil of viscosity $\nu = 20$ cSt, density $\rho = 950$ kg m⁻³, and surface tension $\sigma = 20$ mN/m was vibrated sinusoidally at frequency $f = \omega_0/2\pi = 80$ Hz with peak acceleration γ [see Fig. 1(a) and Ref. 18 for details]. The bath is of diameter 16 cm and is surrounded by a shallow border of width 9 mm and depth 1 mm that serves to damp waves locally. The bath acceleration γ is always below the Faraday threshold $\gamma_F \approx 4.2$ g, at which the interface becomes unstable to a field of Faraday waves with wavelength λ_F prescribed by the standard water-wave dispersion relation.¹⁹ Consequently, the bath would remain quiescent in the absence of the droplet. Droplets of radius R are generated using piezoelectric actuation.²⁰ The corresponding vibration number $\omega_0/\sqrt{\sigma/(\rho R^3)}$ ranges from 0.67 to 0.81 in our study and prescribes the relative magnitudes of the driving acceleration and the drop’s natural frequency.^{21,22} The oil layer has depth h_0 everywhere except above the pillar, where the depth is h_1 . The pillar diameter, d , is varied from 1 mm to 15 mm. A submerged droplet “launcher” guides the droplet toward the pillar.²³ Previous studies have indicated the importance of working in a isolated environment to avoid the influence of

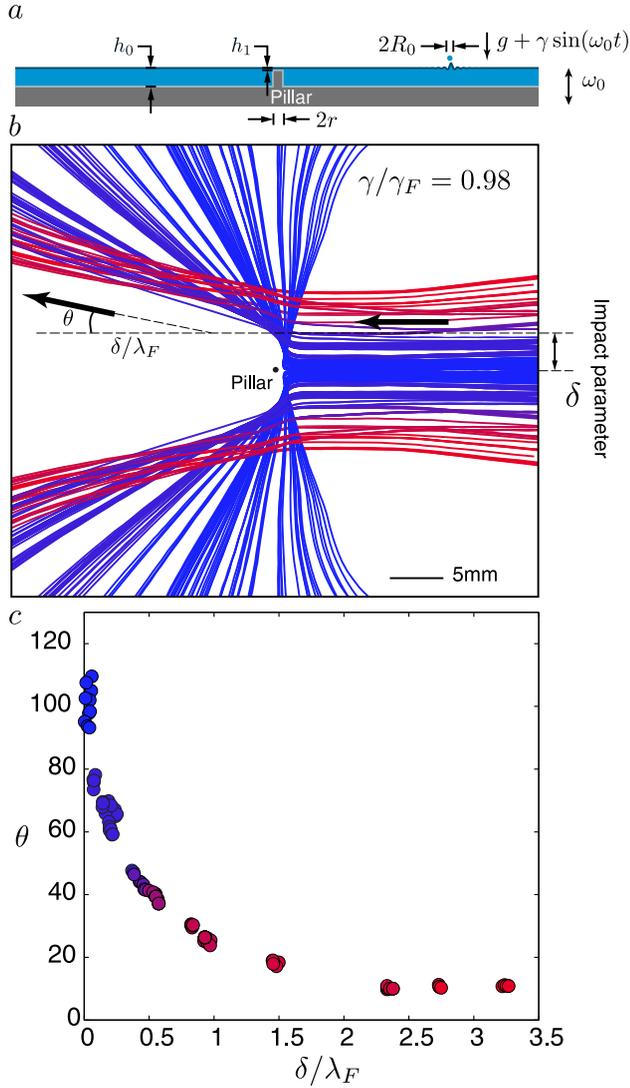


FIG. 1. (a) A fluid bath vibrates vertically with acceleration $\gamma \sin \omega_0 t$. The depth of the bath varies from h_0 in the deep region to h_1 over the pillar. (b) Trajectories of a walking droplet interacting with a submerged pillar of diameter $d = 1$ mm at a fixed vibrational forcing $\gamma/\gamma_F = 0.98$. For these data, $R = 0.38$ mm, $h_0 = 10$ mm, and $h_1 = 0.3$ mm. (c) Dependence of scattering angle θ on impact parameter δ .

ambient air currents,²³ so we use a sealed transparent lid on the vibrating container.

III. SCATTERING

For the smallest pillar examined, $d = 1$ mm, pure scattering trajectories were observed [Fig. 1(b)]. The scattering angle θ , defined as the deviation from the incoming trajectory, decreases monotonically with increasing impact parameter δ defined as the perpendicular distance between the initial droplet path and the pillar center [Fig. 1(c)]. For head-on collisions $\delta \simeq 0$, the drop is deflected such that $\theta > 90^\circ$. The scattering angle then rapidly decreases with increasing δ . For the largest impact parameters considered, $\delta \simeq 3.5\lambda_F$, the drop still interacts with the pillar, and $\theta \simeq 10^\circ$, underscoring the relatively long-range dynamical influence of the pillar as communicated by the droplet's pilot wave field. We note that the observed behavior might be characterized in terms of elastic

scattering, insofar as the incoming and outgoing drop speeds are identical. While the scattering behavior observed for the smallest pillar suggests that the effect of the pillar is repulsive, we shall proceed by demonstrating that, for larger pillars, an initial repulsion may be followed by an attractive tethering phase.

IV. THE LOGARITHMIC SPIRAL

Figure 2(a) illustrates the trajectories arising from scattering from a pillar with diameter $d = 5$ mm for a fixed impact parameter and different values of γ/γ_F ranging from 97% to 99%. In all cases, the drop is initially repelled by the pillar, from a point of closest approach r_{\min} that depends weakly on γ/γ_F . Thereafter, the drops follow a logarithmic spiral with constant radial velocity v_r , azimuthal velocity v_θ , and speed $|\mathbf{v}| = \sqrt{v_r^2 + v_\theta^2}$. The parametric equation for the trajectory is

$$r(\theta) = r_{\min} e^{\frac{v_r}{v_\theta}(\theta - \theta_0)}, \quad (1)$$

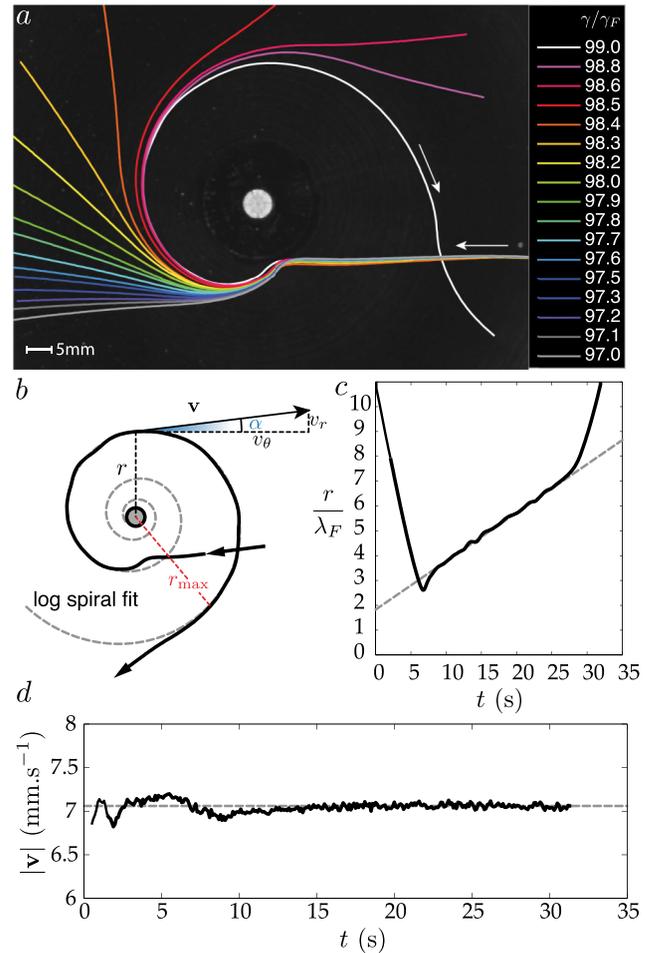


FIG. 2. (a) Observed variation of droplet trajectories as the dimensionless vibrational acceleration, γ/γ_F , increases from 97% to 99%. Pillar diameter is $d = 5$ mm. (b) Individual trajectories are fitted to a logarithmic spiral with pitch angle $\alpha = \arctan(v_r/v_\theta)$. The time evolution of (c) the drop's distance from the pillar center and (d) the droplet speed. When locked onto the spiral trajectory, the droplet moves at a nearly constant speed corresponding to its free walking speed u_0 . Drop diameter, $R = 0.34$ mm, $h_0 = 5.24$ mm, $h_1 = 0.46$ mm. In (b)–(d), $\gamma/\gamma_F = 0.995$.

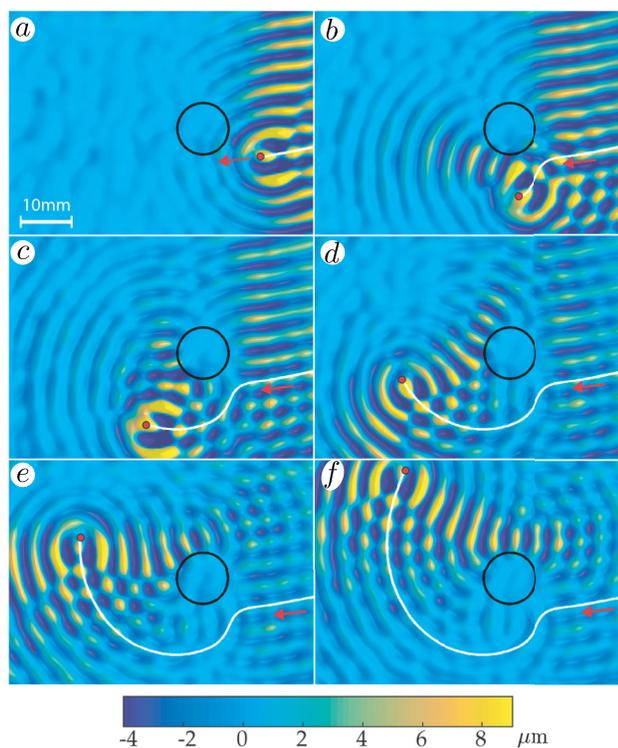


FIG. 3. Surface topography measurements²⁶ of a bouncing droplet with radius and driving acceleration $\gamma/\gamma_F = 0.995$ interacting with a pillar with diameter $d = 10$ mm. The time interval between consecutive images is 1.625 s. The white line indicates the trajectory traced out by the walking droplet, which changes from rectilinear motion to curvilinear motion along a logarithmic spiral. Images correspond to the bath at its maximum vertical displacement. $R = 0.38$ mm, $h_0 = 10$ mm, $h_1 = 0.3$ mm. Reprinted by permission from RightsLink Permissions Springer Customer Service Centre GmbH: Springer Nature, Damiano *et al.*, *Exp. Fluids* **57**(10), 163 (2016). Copyright 2016.²⁶

where $r(\theta_0) = r_{\min}$ denotes the radius at which the drop locks onto the spiral. The ratio of the radial and azimuthal speeds prescribes the spiral's pitch angle $\alpha = \arctan(v_r/v_\theta)$ [see Fig. 2(b)]. The tighter the spiral, the smaller α . Beyond a critical escape radius, or tethering length r_{\max} , the pillar no longer influences the droplet, which resumes its rectilinear free walking state. In Fig. 2(b), we compare the trajectory observed for $\gamma/\gamma_F = 0.995$ to a logarithmic spiral of the form (1) with pitch angle $\alpha \simeq 7.8^\circ$ as inferred from speed measurements ($v_r = 0.96$ mm s⁻¹ and $v_\theta = 6.9$ mm s⁻¹). We note that the instantaneous angular speed of the drop around the pillar, $\Omega = v_\theta/r$, decreases as $1/r$ given the constancy of v_θ .

The pillar affects the droplet's trajectory exclusively through its influence on the pilot wave field. It is thus illuminating to measure the evolution of the wave field during the droplet-pillar interaction using the surface synthetic Schlieren technique.^{25,26} In Fig. 3, we report the surface topography of a drop interacting with a pillar of diameter $d = 10$ mm. Note that the peak amplitude of the waves, $10 \mu\text{m}$, is reduced to less than $1 \mu\text{m}$ above the pillar. The abrupt change of the wave properties above the pillar is a key feature of this problem to be captured in our numerical simulations. Note also the band of relatively intense wave activity on the "tethering line" that may be drawn between the droplet and the pillar.

We proceed by characterizing how the features of such spirals depend on the system parameters. In Fig. 4(a) we show the dependence of the pitch angle α on γ/γ_F for the experimental trajectories displayed in Fig. 2(a). While changing γ has little effect on the drop speed $|\mathbf{v}|$, it does alter the relative magnitudes of v_r and v_θ . The pitch angle is thus found to decrease with increasing γ/γ_F , so the spiral becomes tighter as the waves become more pronounced. We note that the case of a circular trajectory, which would correspond to pillar-induced trapping of the droplet, was not achieved in our experiments.

In Fig. 4(a), we also report the dependence of the tethering length r_{\max} on γ/γ_F . We note that the abrupt increase in r_{\max} above $\gamma/\gamma_F = 0.982$ is likely related to the rapid increase in the spatial extent of the pilot-wave field of the walker as the Faraday threshold is approached.²⁴ In Fig. 4(b), we see the effect of varying the impact parameter δ while holding all other parameters constant. Within the range bounded by the dashed lines in Fig. 4(b), we see that all trajectories obtained experimentally may be collapsed onto a single spiral by simple rotation about the center of the pillar [Fig. 4(c)]. The pitch angle α is thus independent of δ for a pillar of a given size. However, the pitch angle does depend on the diameter d of the pillar. In Fig. 4(d), we show three trajectories observed experimentally with different d . The smaller the pillar, the smaller α . For $d = 3$ mm, the droplet executes a complete revolution around the pillar as it drifts away from it, wobbling around the spiral. Once again, the trapping of droplets onto a circular orbit was not observed for any pillar size or driving acceleration. Since further decreasing d ultimately leads to simple scattering events, one can infer that there is a pillar size at which the pitch angle will obtain a minimum value, allowing for the longest possible spiral.

In order to avoid the influence of the bath's outer boundaries, as may become significant for the largest spirals observed in our laboratory study, we employ the numerical model of Faria,²⁷ which is able to reliably treat walker-boundary interactions. The model was built from the theoretical model of walking droplets developed by Moláček and Bush^{21,28} and from the wave-field modeling of Milewski *et al.*²⁴ and has been benchmarked against experiment for walker-boundary interactions in a number of settings.^{23,27,29} Our simulations indicate that the pitch angle and tethering length r_{\max} are only weakly dependent on pillar depth h_1 over the range considered [Figs. 4(e) and 4(f)]: all trajectories lock onto the same spiral, with their time on the spiral increasing as h_1 decreases. Our simulations also show that the escape radius r_{\max} decreases with h_1 [Fig. 4(f)]. We note that r_{\max} is independent of the impact parameter δ provided the drop locks onto a spiral. Our numerical simulations also demonstrated that the spiral induced by a square pillar is similar to that of a circular pillar with the same diameter, suggesting that the spiral and its features are not strongly sensitive to the pillar shape.

We now seek to infer the pillar-induced force. Moláček and Bush^{21,28} developed a theoretical model for the motion of a drop on a vibrating bath that rationalizes the reported bouncing and walking behaviors.^{22,30} By averaging the forces on the walking droplet over the bouncing period, they developed a trajectory equation describing the drop's horizontal motion

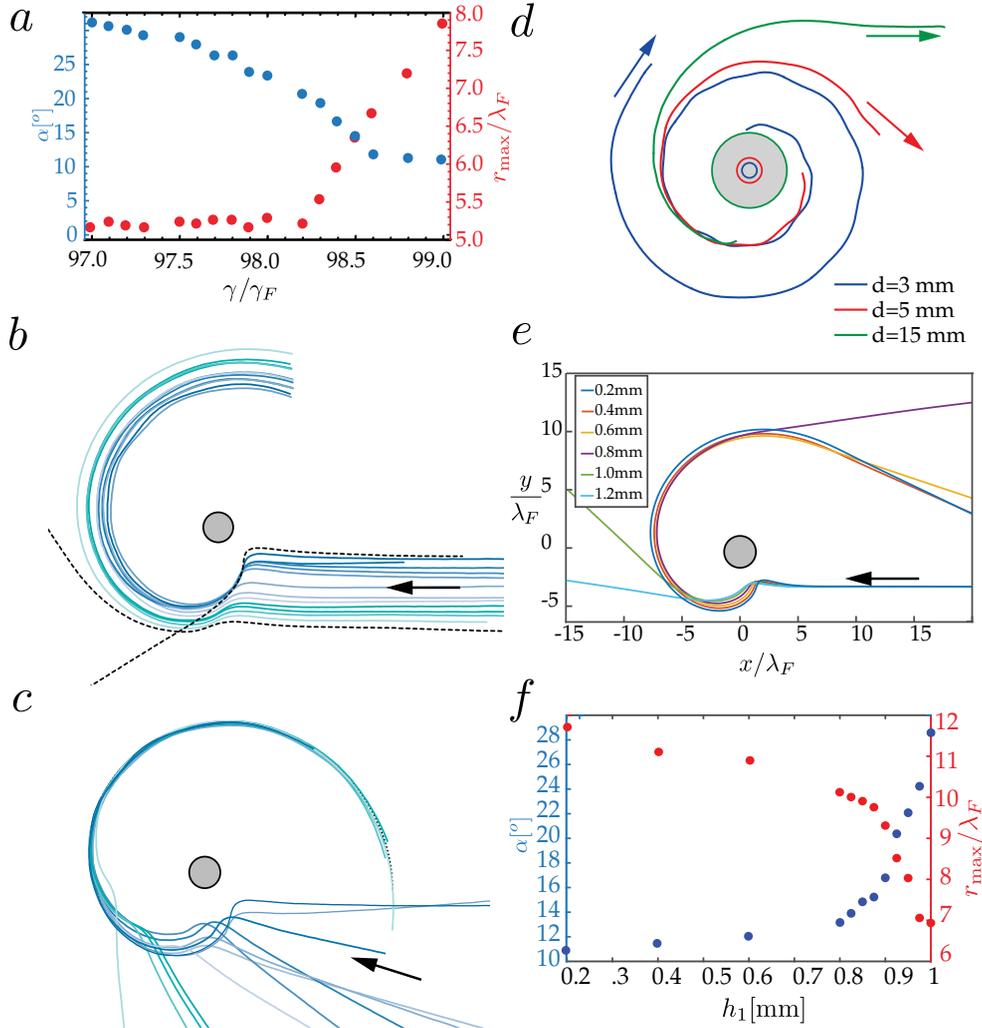


FIG. 4. (a) Observed dependence of pitch angle α and maximum tethering distance r_{\max} on driving acceleration, γ/γ_F , at fixed pillar depth $h_1 = 0.3$ mm for a pillar of diameter $d = 5$ mm. (b) Trajectories within the tethering range, obtained by varying the impact parameter δ , all collapse onto a single spiral (c) upon rotation. Here, $\gamma/\gamma_F = 0.99$ and $d = 5$ mm. (d) Spirals obtained experimentally with three different pillar diameters ($d = 3, 5, 15$ mm) at the same $\gamma/\gamma_F = 0.99$ indicate that the pitch angle decreases with increasing d . (e) Computed trajectories for a pillar of diameter $d = 10$ mm, obtained with different pillar depths h_1 . (f) Computed dependence of pitch angle α and maximum tethering distance r_{\max} on pillar depth h_1 . In all simulations, $R = 0.38$ mm, $h_0 = 6$ mm, $\gamma/\gamma_F = 0.99$.

that was recast in an integro-differential form by Oza *et al.*³¹ Bush *et al.*¹⁷ examined the resulting “stroboscopic” model in the limit of weak droplet acceleration, allowing them to recast the trajectory equation in a temporally local form that is valid in the absence of submerged topography. Specifically, asymptotic expansion of the wave force in the weak-acceleration limit demonstrates that the drop motion may be described in terms of the mechanics of a particle with a speed-dependent mass $m\gamma_B(v)$ and a nonlinear drag force $D_w(v)$ that drives it toward its free walking speed u_0 .³² We describe the overall effect of the pillar on the drop as an instantaneous force \mathbf{F}_p and so write

$$\frac{d(m\gamma_B\mathbf{v})}{dt} + D_w(v)\mathbf{v} = \mathbf{F}_p, \quad (2)$$

where the dependence of the speed-dependent “boost factor” $\gamma_B(v) > 1$ and the nonlinear drag coefficient D_w on the system parameters may be found in Ref. 17.

When the drop walks at its free speed, $v = u_0$, the drag coefficient vanishes $D_w(u_0) = 0$. Consequently, since $|\mathbf{v}| = u_0$ along the spiral, we may describe the walker in terms of

the inviscid dynamics of a particle whose mass depends on its speed. Specifically,

$$m\gamma_B \frac{d\mathbf{v}}{dt} = \mathbf{F}_p. \quad (3)$$

Inserting trajectory equations consistent with the parametric Eq. (1) and the constancy of v_r and v_θ , specifically $r(t) = v_r t + r_{\min}$ and $\theta(t) = v_\theta/v_r * \ln(v_r t + r_{\min}) + \theta_0$, into Eq. (3) reveals a remarkably simple form for the pillar-induced force:

$$\mathbf{F}_p = m\gamma_B \boldsymbol{\Omega} \times \mathbf{v}, \quad (4)$$

where $\boldsymbol{\Omega} = (v_\theta/r)\hat{\mathbf{k}}$ is the instantaneous angular velocity of the drop around the pillar and $\hat{\mathbf{k}}$ is the upward unit vector normal to the undisturbed free surface. We note that, despite the circular symmetry of the system geometry, the pillar-induced force \mathbf{F}_p is not radial, but rather orthogonal to the drop trajectory at all times. The lift force so inferred is thus equivalent in form to a Coriolis force acting on the droplet with boosted mass $m\gamma_B$.

V. CONCLUSION

We have characterized the impact of a walking droplet on a submerged pillar. While the effect of relatively small pillars is to repel the oncoming drop, leading to a simple scattering event, an unexpected effect arises for larger pillars. Specifically, the droplet locks onto a logarithmic spiral whose form is largely independent over a range of impact parameters, but whose pitch angle decreases with γ/γ_F and pillar size. The boost equation¹⁷ has allowed us to infer that, through its influence on the pilot wave field, the pillar induces a lift force $\mathbf{F}_p = m\gamma_B\boldsymbol{\Omega} \times \mathbf{v}$, where $\boldsymbol{\Omega}$ is the instantaneous angular velocity of the pillar around the post. The analogous form of the Coriolis force acting on a mass in a rotating frame and the Lorentz force acting on a charge in a uniform magnetic field⁸ invites the identification of an electromagnetic analog for our system. Dirac's classical theory of radiating electrons predicts that an electron will spiral inwards along a logarithmic spiral in the presence of a uniform magnetic field.³ The outward spirals reported here would presumably arise for the case of electron motion in a uniform magnetic field if the electrons were absorbing energy from their environment (and so maintaining a uniform speed) rather than radiating energy into it.

The pilot-wave dynamics of the walking drops are local in that the instantaneous force acting on the drop is determined by the local wave form at the point of impact. However, the dynamics might also be interpreted as non-local in both space and time in the sense that the wave form at the point of impact depends on both the walker's history and its environment.³⁰ The logarithmic spiral discovered here provides a new macroscopic example of how a local pilot-wave dynamics can give rise to the inference of a nonlocal force, or how pilot-wave-mediated local forces can give rise to apparent action at a distance.

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